4.) A hanging mass is attached to a string which is threaded over a massive pulley and attached to a second mass sitting on a frictionless incline. Known is:

$$
m_1
$$
, m_h , m_p , R , g , θ , and $I_{cm\ of pulley} = \frac{1}{2} m_p R^2$

a.) Ignoring the forces acting at the pulley's $\overline{}$ pin, draw a f.b.d. identifying all the forces acting on both masses and the pulley.

b.) Determine the *moment of inertia* of an axis R/3 units from the center of and perpendicular to an axis through the axle of the pulley.

$$
m_1
$$
, m_h , m_p , R , g , θ , and $I_{cm\ of\ pulley} = \frac{1}{2} m_p R^2$

1

c.) The system begins to accelerate. What is the magnitude of that *acceleration*? (Assume the acceleration is down the incline.)

d.) What is the pulley' s *angular acceleration*?

e.) The hanging mass drops from rest a distance "h." What is its *velocity* magnitude by the end of the drop? (This could happen if the hanging mass was slowing down.) m_1 , m_h , m_p , R, g, θ, and I_{cm of pulley} = 1 2 $\rm m_pR^2$

f.) What is the *angular velocity* of the pulley at that point?

g.) What is the *angular momentum* of the pulley at that point?

4.) A hanging mass is attached to a string which is threaded over a massive pulley and attached to a second mass sitting on a frictionless incline. Known is:

$$
m_1
$$
, m_h , m_p , R, g, θ , and $I_{\text{cm of pulley}} = \frac{1}{2} m_p R^2$

a.) Ignoring the forces acting at the pulley's pin, draw a f.b.d. identifying all the forces acting on both masses and the pulley.

b.) Determine the *moment of inertia* of an axis R/3 units from the center of and perpendicular to an axis through the axle of the pulley.

Using the parallel axis theorem, we get:

 $I_p = I_{cm} + md^2$ $=$ 1 2 $m_pR^2 + m_p$ R 3 $\sqrt{2}$ ⎝ $\left(\frac{R}{2}\right)$ ⎠ ⎟ 2 $=$ 11 18 $m_{\overline{p}}R^2$

Note that if the hanging mass drops, the mass on the incline goes UP the incline:

$$
\sum \text{KE}_{1} \sum \text{U}_{1} + \sum \text{W}_{ext} = \sum \text{KE}_{2} + \sum \text{U}_{2}
$$

\n
$$
0 + [m_{h}gh] + 0 = \left[\frac{1}{2}m_{1}v^{2} + \frac{1}{2}m_{h}v^{2} + \frac{1}{2}I_{pulley}\omega^{2}\right] + [m_{1}g(h\sin\theta)]
$$

\n
$$
\Rightarrow [m_{h}gh] = \left[\frac{1}{2}m_{1}v^{2} + \frac{1}{2}m_{h}v^{2} + \frac{1}{2}\left(\frac{1}{2}m_{p}\mathbf{R}^{2}\right)\left(\frac{v}{\mathbf{R}}\right)^{2}\right] + [m_{1}g(h\sin\theta)]
$$

\n
$$
\Rightarrow v = \sqrt{\frac{2(m_{h}gh - m_{1}g(h\sin\theta))}{m_{1} + m_{h} + \frac{m_{p}}{2}}}
$$

$$
m_1
$$
, m_h , m_p , R , g , θ , and $I_{cm \ of pulley} = \frac{1}{2} m_p R^2$

f.) What is the *angular velocity* of the pulley at that point?

$$
\omega = \frac{v}{R}
$$

g.) What is the *angular momentum* of the pulley at that point?

$$
L = I_{\text{pin}} \omega
$$